

FLEXIBLE FREE STANDING SU-8 MICROFLUIDIC IMPEDANCE SPECTROSCOPY SENSOR FOR 3D MOLDED INTERCONNECT DEVICES APPLICATION

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Abstract:

Current contribution reports a new microfluidic impedance spectroscopy sensor that is applicable for direct attachment on 3D molded interconnect devices (3D-MID). The Sensor is made of flexible SU-8 polymer featured by the system of electrodes structured directly on SU-8. Sensor chip is able to be directly soldered on MID due to electroless plated Nickel contact pads. Due to opposite electrodes design and one side direct shielded attachment, sensor is able to be applied for measurements in intensive electromagnetic environment. To the best of our knowledge none of such sensors has been previously reported.

Key words: SU-8, 3D-MID, microfluidic impedance spectroscopy

Introduction

Impedance spectroscopy is a well-known method for liquid analysis [1]. For decades it is applied in microfluidic systems for liquid properties determination [2,3]. Depending on the microchannel material, microfluidic sensors can be performed on a wafer basis [4,5] or it can be completed as a free-standing structure that is applicable for 3D attachment. When microfluidic sensor is completed on a wafer level, it demonstrates a number of advantages, but at the same time remains not applicable for usage within 3D systems.

During the last years, molded interconnection devices (MIDs) are attracting considerable attention. Structures completed within MID technology can be applied as a 3D detail of a system, but at the same time having all required electrical interconnections, circuit elements and sensors directly on it. Due to the injection molding and metallization process a wide range of 3D-shaped substrates are fabricable, Fig. 1. In order to be applied in such 3D systems, it is required from sensor to have a flexible origin with further possibility for 3D direct MID attachment.

Manufacturing of free-standing microfluidic structures can be completed under different approaches [6]. PDMS material is well known

regarding microfluidic structures manufacturing [7]. It is considerably low cost material, but it cannot be directly structured with photolithography. In order to structure PDMS, different techniques such as micro-molding are needed to be applied that can considerably affect resolution of a final microfluidic structures.

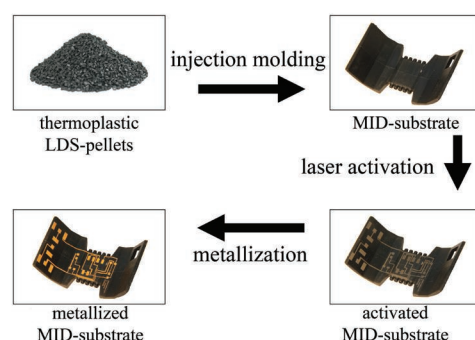


Fig. 1. Fabrication process of a microfluidic 3D-MID with laser direct structuring LDS

Polyimide is also widely applied as a material for microfluidic sensors especially for medical applications [8]. The same way as PDMS, polyimide does not provide a possibility for direct structuring with lithographical methods and normally, dry etching process is needed to be performed for that.

SU-8 is already very well-known photoresist that is widely used as a construction material for microfluidic structures, sensors and wide variety of different applications. Based on EPON-Resin SU-8 is chemically stable and optically transparent material with controllable mechanical properties through its processing and possibility to be directly structured with a standard photolithography process [9,10].

Lots of wafer based SU-8 microfluidic structures have been already published [11,12], but completely free-standing SU-8 microfluidic structures are rarely declared due to certain complexity of structuring of metal layers on SU-8 and releasing step technology for millimeter scale structures.

In [13] the fabrication of a SU-8 thermal flow sensor with manual Kapton film releasing was demonstrated. Releasing was completed only from one side of the channel finalizing pure SU-8 encapsulation of microfluidic structures. Completed microfluidic sensor, after releasing step, is still remains on second PMMA holding wafer and is not applicable for 3D attachment. The same Kapton film releasing steps were applied in [14] where final SU-8 free-standing cantilever structures were embedded in a SU-8 on silicon based structures and in [15] where SU-8 multilayer microstructures were adhesive bonded and released with Kapton film. In all of referred contributions, final microfluidic structures remained on a handling wafer that makes them not applicable for 3D attachment.

Recently, the new nanoscale sacrificial releasing layer Omnicat™ was introduced and applied for SU-8 structures releasing [16]. Initially aimed to be used for stripping of SU-8 molds in which metal structures are electroplated, it has become a very convenient and considerably clean method for SU-8 microfluidic structures wet releasing [17]. In current contribution we demonstrate SU-8 based technology with Omnicat™ releasing step that affords to achieve completely free-standing SU-8 based microfluidic sensors.

In comparison to previously published results, in current contribution we demonstrate an impedance spectroscopy sensor with metal electrode structures completely integrated in SU-8 and released from both sides resulting completely free-standing and flexible SU-8 based sensor. Manufactured SU-8 free standing microfluidic sensor is applicable for subsequent 3D-MID attachment that gives an opportunity to create reduced-scale sensor devices for 3D applications.

Fabrication of the sensor device

The fabrication process of the sensor was divided into three parts, Fig. 2. First the fabrication was completed with silicon wafer where SU-8 microfluidic structures and sensor bottom electrodes were defined Fig.2 Part 1. It starts with the cleaning of the 100 mm silicon wafer with an HF 1 % dip for 1 min. An adhesion layer of Omnicat™ was spun on the clean substrate and baked for 1 min on a hotplate at 200 °C. In order to improve releasing speed, thickness of Omnicat™ was enlarged by subsequent multilayer coating. Next SU-8-50 handling layer was coated on the Si wafer in a thickness of 50 µm without any structures. After the first SU-8 layer coating the bottom electrode (Titanium (30 nm) and Platinum (300 nm)) of the sensor chip was deposited on the polymer and structured via Lift-Off. The surface of the SU-8 was pretreated with plasma of O₂/SF₆ to improve the adhesion between the polymer and metal electrodes. After stripping the photoresist layer a 50 µm thick SU-8-50 layer was spin coated and structured to implement the microfluidic channels. To avoid thermal mechanical stress all baking processes were temperature ramped.

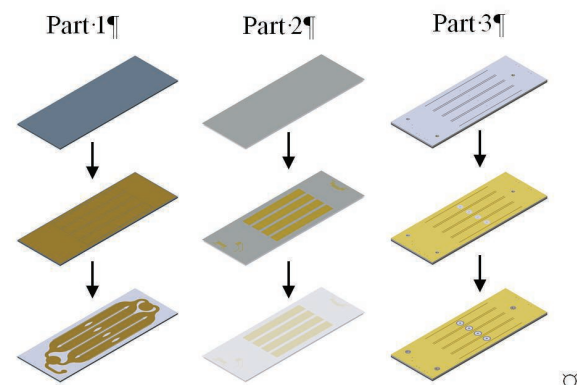


Fig. 2. Fabrication of the complete sensor, Part 1 fabrication of the bottom electrode and the microfluidic channels of the sensor chip, Part 2 manufacturing of the top electrode and the SU-8 top cap, Part3 establishing of the bonding, dry etching and plating of the contact structures

Next part of sensor manufacturing was including fabrication of sensor top electrodes structures on SU-8/glass wafer Fig.2 Part 2. Borosilicate glass was cleaned in a solution of H₂SO₄ and H₂O₂ at 135 °C for 10 min and then coated with Omnicat™ for further releasing of the next 50 µm thick layer of SU-8-50. A plasma treatment was performed to activate the surface of the polymer layer improving the adhesion of subsequently sputtered Ti/Pt metal layer that was further Lift-Off structured. The layer was then covered with a thin film of SU-8-5. A second exposure step (dose of 250 mJ/cm²)

opened the possibility for an additional crosslinking of the SU-8-5 layer in the following bonding step. Processed within first and second steps wafer based structures were adhesive bonded after the exposure with an assistance of a SUSS MA6/BA6 mask aligner and a SUSS SB6e substrate bonder. After the bonding step the glass wafer was released in an etchant.

On top of the SU-8 a 200 nm Aluminum layer was sputtered and structured via lithography and etching. The Al mask was used in Oxford Instruments PlasmaSystem100 dry etching process to open the polymer layers and establish the entry for the top sensor electrode contact and the sidewalls for the shielding. To avoid any thermal mechanical stress of the SU-8 layer during the plasma etching process the Si handling wafer was cooled with helium and the etching was divided into steps of 30 sec with the mixture of SF_6/O_2 . The mask material was stripped and a new metal layer of 30 nm Pt and 500 nm Al were structured with a Lift-Off process to connect the top electrodes and establish the 3D-shielding. To realize the solder connections a final photoresist Ti Spray was spray coated with a SUSS Delta Altaspray. By using an electroless metallization bath the final layers of nickel and gold were plated. After the metallization the completed SU-8 multilayer structures were separated from the Si handling wafer by a releasing step of the OmnicoatTM in MF-319 developer.

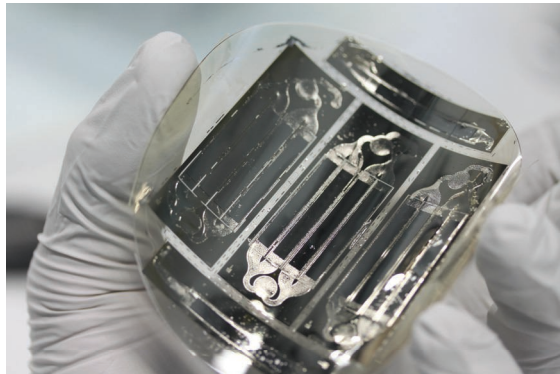


Fig. 3. Completed SU-8 based free standing impedance spectroscopy sensors on a 100 mm-substrate with different designs.

Experimental results

Completely fabricated free standing microfluidic sensors intended for further dicing are shown in Fig. 3. Sensors are completed within a 4" size and demonstrate sufficient flexibility for 3D attachment. SEM image of a section of free standing microfluidic channel is shown in Fig. 4. As it can be seen, there is no boundaries between different layers of SU-8 can be observed and side walls are almost vertical.

Bonding area is completely closed without defects even after sample dicing.

The self-developed 3D-MID platform was injection molded in our lab under help of an ARBURG 320s equipment. The 3D-MID substrate integrates all electrical as well as fluidic interconnections between microfluidic chip, measuring device and sensor itself and is shown in Fig. 5.

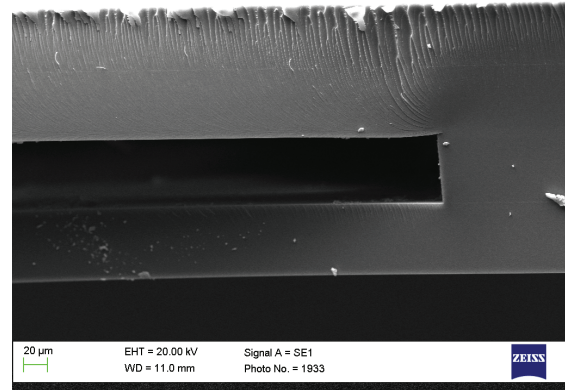


Fig. 4. SEM image of a free standing microfluidic channel.

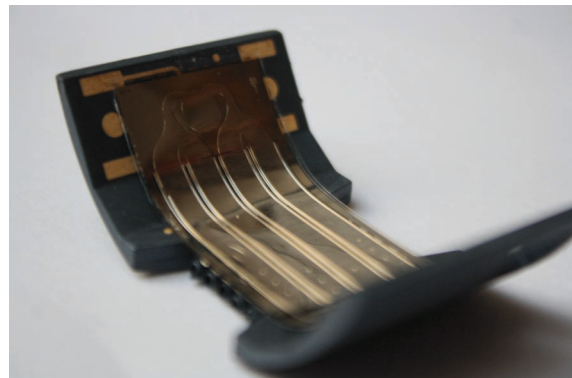


Fig. 5. Impedance spectroscopy sensor directly attached on a 3D-MID.

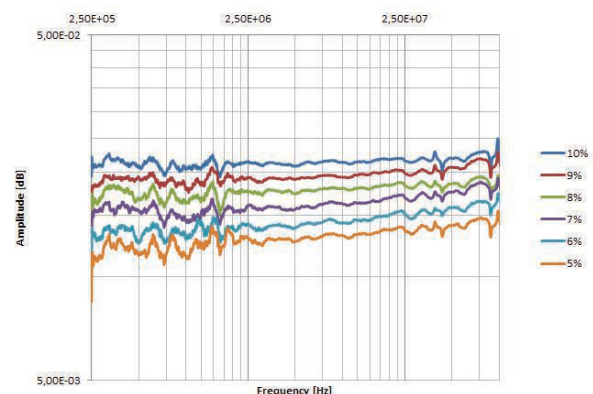


Fig. 6. Sensor S_{21} parameter measurement results of mixture of water and ethanol in a frequency range of 0,25 MHz and 250 MHz.

Due to sensor's plated contact pads, it is able to be directly attached to 3D-MID platform by solder process without additional chip wire

bonding. The microfluidic part of the 3D-MID was connected to a fluid system which contained a micro pump, a reservoir and a temperature control unit. The electrical ports of the MID were wired with a FPGA based self-developed NWA for the measurement. Sensor measurement results of water – ethanol mixture are shown in Fig. 6. Measurements were made at a constant temperature of 30 °C and demonstrate sufficient sensitivity to ethanol concentration.

Conclusions

Demonstrated technology for manufacturing of free-standing SU-8 structures provides a possibility to fabricate SU-8 based completely free-standing microfluidic sensor structures. Completed on SU-8 sensor electrodes demonstrate feasibility of standard lift-off metal layers processing on SU-8 coated wafers. Technology of “buried” in SU-8 metal electrodes provides a reliable structures with a considerably low cost processing. Control of SU-8 processing parameters makes it possible to achieve flexible and mechanically stable structures that can be applied for 3D attachment on a 3D molded interconnection device. Releasing steps completed with standard Omnicoat™ processing gives an opportunity for considerably clean wet SU-8 releasing even with relatively large scale structures as it was demonstrated on Fig. 3 the whole 4” wafer was released without any structures damage. Sensor was assembled on 3D-MID platform integrating all electrical and fluidic interconnections. Fabricated sensor measurement results demonstrate high sensitivity to ethanol concentration analyzing water-ethanol mixtures.

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